## Amendments to the Claims

- 1. (original) A device for grabbing bottles, the device comprising:
  - a frame having a first and a second parallel elongated support structure;
  - a first set of gripping heads mounted on said first elongated support structure;
  - a plurality of shoulder pads each adjacent to said first set of gripping heads, said plurality of shoulder pads mounted on said first elongated support structure;
  - a plurality of extendable arms mounted on said second elongated support structure; and a second set of gripping heads mounted on an end of said plurality of extendable arms.
- 2. (original) The device according to claim 1, further comprising an interface for connecting said device to an automated system.
- 3. (original) The device according to claim 2, wherein said set of gripping heads each comprises:
  - a motorized base; and
  - a plurality of claws mounted on said motorized base, said motorized base enabling said claws to securely grip.
- 4. (original) The device according to claim 3, further comprising a pressure sensor mounted on each of said second set of gripping heads for sensing an overload of said plurality of extendable arms.
- 5. (currently amended) A device comprising:
  - a frame;
  - a first set of gripping heads mounted on said frame;
  - a plurality of shoulder pads each surrounding each of said first set of gripping heads, said plurality of shoulder pads mounted on said frame; [[and]]
  - a second set of gripping heads adjacent to said first set of gripping heads[[.]]; and
  - a plurality of extendable arms each supported by said frame, said plurality of extendable arms each having a first end and a second end, said second set of gripping heads each mounted on said first end.



- 6. (original) The device according to claim 5 wherein said first set of gripping heads each further comprises:
  - a motorized base; and
  - a plurality of claws mounted on said motorized base, said motorized base enabling said claws to securely grip.
- 7. (original) The device according to claim 5 wherein said second set of gripping heads each further comprises:
  - a motorized base; and
  - a plurality of claws mounted on said motorized base, said motorized base enabling said claws to securely grip.
- 8. (cancelled)
- 9. (currently amended) The device according to claim 5[[8]] further comprising an interface for connecting the gripping device to an automated system.
- 10. (currently amended) The device according to claim 5[[8]] further comprising a pressure sensor connected with said plurality of gripping heads for sensing an overload of said plurality of gripping heads.
- 11. (currently amended) A device for grapping a bottle having a neck comprising: a plurality of claws mounted on said motorized base, said motorized base enabling said claws to securely grip and;
  - a sensor for sensing an amount of stress created on the device by a weight of the bottle.
- 12. (cancelled)
- 13. (original) The device according to claim 11, wherein said plurality of claws mate with the neck of bottle.
- 14. (original) The device according to claim 13, wherein said plurality of claws each further comprise a pad mounted on each of said plurality of claws for supporting the neck of the bottle.

- 15. (cancelled)
- 16. (cancelled)
- 17. (cancelled)

arms.

(original) A method of loading and unloading bottles using a device, the method comprising:

loading a plurality of bottles with a device at a first location; and unloading said plurality of bottles with said device at a second location, wherein said device further comprises:

a frame having a first and a second parallel elongated support structure; a first set of gripping heads mounted on said first elongated support structure; a plurality of shoulder pads each adjacent to said first set of gripping heads, said plurality of shoulder pads mounted on said first elongated support structure; a plurality of extendable arms mounted on said second elongated support structure; and a second set of gripping heads mounted on an end of said plurality of extendable

19. (new) A device for unloading a rack storing containers, wherein: the rack has a first cell storing a first container and a second cell storing a second container;

the first container blocks removal of the second container by the device; and the device comprises an extending arm that extends through the first cell into the second cell.

- 20. (new) The device of claim 19, wherein the extending arm extends through a space previously occupied by the first container once the first container is removed from the rack.
- 21. (new) The device of claim 19, wherein the extending arm comprises at least one gripping head that grips a container being removed.

- 22. (new) The device of claim 21, further comprising at least one shoulder pad coupled to the extending arm and positioned to support a container being removed.
- 23. (new) The device of claim 19, wherein the extending arm has a closed length and a fully extended length, the difference of which is greater than a longest length of the first container.
- 24. (new) The device of claim 19, wherein the extending arm comprises at least one gripping head and at least one should pad that supports a container being loaded into the rack.
- 25. (new) The device of claim 19, further comprising a loading arm comprising at least one gripping head and at least one shoulder pad that supports a container being loaded into the rack.
- 26. (new) The device of claim 25, wherein a maximum diameter of the loading arm is less than a maximum diameter of the first container.
- 27. (new) A device for grabbing a container, comprising a loading arm having at least one gripping head and at least one shoulder pad that support the container during loading of the rack.
- 28. (new) The device of claim 27, wherein a maximum diameter of the loading arm is less than a maximum diameter of the container.
- 29. (new) The device of claim 27, wherein the container is defined by a cylindrical body and a conical shoulder and the at least one shoulder pad contacts the conical shoulder, not the cylindrical body when the container is grabbed.